

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE
APPLICATION FOR PATENT

**METHOD AND APPARATUS FOR DETERMINING FAULT SOURCES FOR
DEVICE FAILURES**

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FIELD OF THE INVENTION

The present invention generally relates to failure analysis techniques and in particular, to a method and apparatus for determining fault sources for device failures.

BACKGROUND OF THE INVENTION

As product life cycles shorten, rapid yield improvement becomes critical. In the area of semiconductor devices, for example, a major part of the yield improvement effort has traditionally involved failure analysis on devices that fail electrical test. Once fault sources for device failures are determined, the information is fed back to the fabrication facility for corrective action.

In order to determine such fault sources, however, a large amount of data often must be processed. When such data is analyzed manually, the task can be especially daunting. United States Patent No. 5,475,695, entitled "Automatic Failure Analysis System," invented by John M. Caywood et al., and incorporated herein by this reference, describes an automatic failure analysis system for processing test data to identify failure causing defects.

Even in an automatic failure analysis system, however, it is useful to improve the computational efficiency for determining fault sources for device failures, because such improvement translates directly into accelerating the yield analysis and consequently, yield improvement curve. As a result, devices can be produced with higher yields sooner, thereby improving manufacturing throughput and reducing unit cost earlier in the product life cycle of the device.

OBJECTS AND SUMMARY OF THE INVENTION

Accordingly, an object of the present invention is a method for determining fault sources for device failures that is computationally efficient.

Another object is an apparatus for performing a method for determining fault sources for device failures that is computationally efficient.

These and additional objects are accomplished by the various aspects of the present invention, wherein briefly stated, one aspect is a method for determining fault sources for device failures, comprising: generating failure signatures of fault sources for preselected tests; generating aggregate failure signatures for individual of the fault sources from the failure signatures; generating aggregate device test data from test data of a device for the preselected tests; generating aggregate matches by comparing the aggregate failure signatures with the aggregate device test data; and determining fault sources for device failures by comparing the test data of the device with ones of the failure signatures of fault sources corresponding to the aggregate matches.

Another aspect is an apparatus for determining fault sources for device failures, comprising at least one circuit configured to: generate failure signatures of fault sources for preselected tests; generate aggregate failure signatures for individual of the fault sources from the failure signatures; generate aggregate device test data from test data of a device for the preselected tests; generate aggregate matches by comparing the aggregate failure signatures with the aggregate device test data; and determine fault sources for device failures by comparing the test data of the device with ones of the failure signatures of fault sources corresponding to the aggregate matches.

Another aspect is an apparatus for determining fault sources for device failures, comprising: means for generating failure signatures of fault sources for preselected tests; means for generating aggregate failure signatures for individual of the fault sources from the failure signatures; means for generating aggregate device test data from test data of a device for the preselected tests; means for generating aggregate matches by comparing the aggregate failure signatures with the aggregate device test data; and means for determining fault sources for device failures by comparing the test data of the device with ones of the failure signatures of fault sources corresponding to the aggregate matches.

Additional objects, features and advantages of the various aspects of the invention will become apparent from the following description of its preferred embodiments, which description should be taken in conjunction with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 illustrates, as an example, a method for determining fault sources for device failures, utilizing aspects of the present invention.

FIG. 2 illustrates, as an example, a data flow diagram of a method for determining fault sources for device failures, utilizing aspects of the present invention.

FIG. 3 illustrates, as an example, an application of a method for determining fault sources for device failures, utilizing aspects of the present invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

FIG. 1 illustrates a method for determining fault sources for device failures. A processor programmed to perform the method is the preferred implementation. In **101**, failure signatures of fault sources are generated for preselected tests to be performed on units of a device. One method of doing this is to determine potential defect failures by analyzing the physical layout of the device using, for example, an expert system, and determine failure signatures corresponding to the potential defect failures using, for example, a knowledge database. As an example, the knowledge generation portion of the aforementioned United States Patent No. 5,475,695, entitled "Automatic Failure Analysis System," describes a system useful for generating such failure signatures.

Examples of failure signatures for a memory device include: a column failure where a column of bits or cells fails throughout a block of bits; a column quad failure where four adjacent columns of bits fail; a row failure where a row of bits fails throughout a block; a column

fragment failure where a fragment of a column of bits fails;
a row fragment failure where a fragment of a row of bits
fails; an even/odd bit pair in a column failure; an odd/even
bit pair in a column failure; an even/odd bit pair in a row
5 failure; an odd/even bit pair in a row failure; and a single
bit failure where a single bit fails surrounded by good
bits. Such examples are merely representative. There are
many well-known failure signatures for memory devices that
are not included above. For other types of devices, other
10 failure signatures may also be generated.

In **102**, aggregate failure signatures are generated
from the failure signatures for individual of the fault
sources. One method of doing this is to logically combine
failure signatures corresponding to the preselected tests
15 for individual of the fault sources, such as, for example,
described in reference to file **31** of **FIG. 3**, where OR logic
is used to logically combine or aggregate failure signatures
corresponding to individual of the preselected tests for
individual of the fault sources. Where the failure
20 signatures are defined as bitmap patterns, such as with a
memory or programmable logic array ("PLA") device, the
bitmap patterns, particularly if they are of different size,
are preferably centered with respect to each other before
their aggregation.

In **103**, test data is received that corresponds to
the preselected tests having been performed on one or more
units of a particular device of interest. In the case of an
array type device such as a memory or PLA, the test data is
commonly in the form of bitmaps indicating which cells or
30 bits in the array have failed. In **104**, aggregated test data
is generated from the previously received test data. One
method of doing this is to logically combine the test data,
such as, for example, described in reference to file **33** of

FIG. 3, where OR logic is used to logically combine or aggregate the device test data.

Since **101** and **102** only require device design data, they may be performed prior to actual fabrication of any units of the device of interest. In contrast, since **103** and **104** require actual device test data, they can only be performed after fabrication of units of the device. Therefore, **101** and **102** are described herein as being performed prior to **103** and **104**. However, it is to be appreciated that such order is not restrictive. In certain applications, **101** and **102** may be performed after **103** and **104**, and this alternative order is contemplated to also be included within the full scope of the appended claims.

In **105**, aggregate matches are generated by comparing the aggregate failure signatures with the aggregate device test data. One method of doing this is to search the aggregate test data for the aggregate failure signatures. For array type devices where bitmap device test data and bitmap failure signature patterns are used, the aggregate bitmap failure signature patterns are "moved" through the aggregate bitmap device test data in much the same manner as conventional techniques wherein non-aggregated bitmap failure signature patterns are "moved" through non-aggregated bitmap device test data to detect instances of such non-aggregated bitmap failure signature patterns occurring in the non-aggregated bitmap device test data. In the present method, since aggregate test data and aggregate failure signatures are used, there is far less data to be compared than in the conventional techniques wherein non-aggregated bitmap failure signature patterns are "moved" through non-aggregated bitmap device test data, thus speeding up the fault source identification process.

In **106**, fault sources for device failures are then determined by comparing the original test data with the failure signatures of fault sources corresponding to the aggregate matches. One way of doing this is to first
5 determine the fault sources corresponding to the aggregate matches, then for individual of the fault sources, compare test data of the device for individual of the preselected tests against failure signatures of the fault sources for those individual of the preselected tests. Fault sources
10 for device failures are then determined by finding matches through such comparing of the test data against the failure signatures.

FIG. 2 illustrates, as an example, a data flow diagram of a method for determining fault sources for device
15 failures. File **201** includes predicted failure signatures generated, for example, as described in reference to **101** in **FIG. 1**. In this example, each predicted failure signature is associated with a fault source (also referred to herein simply as a "fault") and a test to be performed on the
20 device, such that when the fault is present in the device, the predicted failure signature occurs in the results of the test. File **202** includes aggregate failure signatures generated, for example, as described in reference to **102** of **FIG. 1** from the predicted failure signatures of file **201**.
25 File **203** includes bitmaps conventionally generated from test data provided from a device tester for tested units of a device. Each bitmap in this example results from a test performed on one unit of the device. File **204** includes an aggregate bitmap generated, for example, as described in
30 reference to **104** of **FIG. 1** from the bitmaps in file **203**. In this and other examples described herein, there is one such aggregate bitmap for individual unit of the device.

A failure classification processor **205** reads the contents of files **202** and **204**, generates aggregate matches, and determines fault sources corresponding to those aggregate matches as described, for example, in reference to list **34** in **FIG. 3**. This matching process is referred to as being level 1, because it is done at the aggregate level so as to provide a "coarse-tuned" list **206** of potential fault sources. A second failure classification processor **207** reads the "coarse-tuned" list **206** and the contents of files **201** and **203**, and determines a "fine-tuned" list of potential fault sources for device failures, as described, for example, in reference to list **35** in **FIG. 3**. This matching process is referred to as being level 2, because it is done at the non-aggregate level to provide the "fine-tuned" list **208** from the "coarse-tuned" list **206**. Where more than one potential fault source may be associated with an aggregate match in the "fine-tuned" list **208**, information regarding their probabilities of occurrence are also preferably provided for or otherwise linked to the list **208**.

FIG. 3 illustrates, as a simplified example, an application of a method for determining fault sources for device failures. File **30** includes predicted fault signatures **301~306**, such as those described in reference to file **201** in **FIG. 2**. Although all of the predicted failure signatures are shown as being the same 3x3 bit or cell size, in practice, it is to be appreciated that they may be different sizes and also not necessarily of equal rows and columns. In the example, a "0" in a bit or cell location indicates that no failure is detected for that bit or cell, and conversely, an "F" in a bit or cell location indicates that a failure is detected for that bit or cell.

If fault 1 is present in the device being tested, then predicted fault signature **301** is expected to occur in the results of test A and predicted fault signature **304** is expected to occur in the results of test B. On the other hand, if fault 2 is present in the device being tested, then predicted fault signature **302** is expected to occur in the results of test A and predicted fault signature **305** is expected to occur in the results of test B. Finally, if fault 3 is present in the device being tested, then predicted fault signature **303** is expected to occur in the results of test A and predicted fault signature **306** is expected to occur in the results of test B.

It is noteworthy that sometimes a failure may not be detected in the results of a test, even though a fault source may be present in the device being tested. Predicted failure signatures **304** and **303** are representative of such occurrences. Therefore, it is useful to perform multiple tests on a device. Although only two tests, A and B, are shown in this simplified example, it is to be appreciated that in practice, many more tests are preferably performed on units of a device to assure detection of as many fault sources as commercially practical.

File **31** includes aggregate fault signatures **311~313**, such as and exemplary of those described in reference to file **202** in **FIG. 2**. Aggregate fault signature **311** is generated by logically OR'ing fault signatures **301** and **304**. Likewise, aggregate fault signature **312** is generated by logically OR'ing fault signatures **302** and **305** associated with fault 2, and aggregate fault signature **313** is generated by logically OR'ing fault signatures **303** and **306** associated with fault 3.

File **32** includes bitmaps **321** and **322** resulting respectively from tests A and B being performed on one unit of the device. Although bitmaps **321** and **322** are depicted as being the same size as the predicted failure signatures
5 **301~306**, in practice, it is to be appreciated that they are generally much larger. For example, for a large memory device, resulting device bitmaps may have rows and/or columns in the order of thousands. In such a case, bitmaps **321** and **322** may be considered 3x3 arrays that have the same
10 respective coordinates in their respective larger bitmaps, wherein at least one of bitmaps **321** and **322** includes a failure signature whose fault source is to be determined.

File **33** includes an aggregate bitmap **331**, such as and exemplary of those described in reference to file **204** in
15 **FIG. 2**. Aggregate bitmap **331** is generated in this example by logically OR'ing bitmaps **321** and **322**.

A "coarsely-tuned" or level 1 classification list **34** of potential fault sources includes fault 1 and fault 3, as determined, for example, by a processor such as described
20 in reference to the failure classification processor **205** of **FIG. 2**. To generate the "coarsely-tuned" list **34**, the processor compares each of the aggregate failure signatures **311~313** in turn, with the aggregate bitmap **331**. Each time a match occurs between one of the aggregate failure signatures
25 **311~313** and the aggregate bitmap **331**, an aggregate match is noted. The processor then determines fault sources corresponding to the aggregate matches and adds them to the "coarsely-tuned" list **34**. In particular in the present
30 example, aggregate failure signatures **311** and **313** both match aggregate bitmap **331**, so both aggregate failure signatures **311** and **313** are noted as aggregate matches and faults 1 and

3 respectively corresponding to aggregate failure signatures
311 and **313** are added to the "coarsely-tuned" list **34**.

In the case where the aggregate bitmap **331**
represents a portion of a much larger device bitmap, the
processor "moves" each of the aggregate failure signatures
311~313 in turn, through the larger device bitmap in a
conventional raster scan fashion, for example, from left to
right and top to bottom. Each time a match occurs between
one of the aggregate failure signatures **311~313** and an
aggregate bitmap **331** representing a portion of the larger
device bitmap, an aggregate match is noted and the processor
determines the corresponding fault source and adds it to the
"coarsely-tuned" list **34**.

A "finely-tuned" or level 2 classification list **35**
of potential fault sources includes only fault 1, as
determined, for example, by a processor such as described in
reference to the failure classification processor **207** of
FIG. 2. To generate the "finely-tuned" list **35**, the
processor reads the fault sources included in the "coarsely-
tuned" list **34**, and compares the non-aggregate failure
signatures associated with each of those fault sources
against their test corresponding, non-aggregate bitmaps.
When matches occur for all such comparisons for a fault
source, that fault source is added to the "finely-tuned"
list **35**. When a match does not occur for any such
comparison for a fault source, that fault source is omitted
from the "finely-tuned" list **35**.

In particular in the present example, the
processor compares fault signature **301** (for fault 1, test A)
against bitmap **321** (for test A) and determines that they
match, and it compares fault signature **304** (for fault 1,
test B) against bitmap **322** (for test B) and determines that

they also match. Consequently, it adds fault 1 to the
"finely-tuned" list **35**. On the other hand, the processor
compares fault signature **303** (for fault 3, test A) against
bitmap **321** (for test A) and determines that they do not
5 match, and it compares fault signature **306** (for fault 3,
test B) against bitmap **322** (for test B) and determines that
they also do not match. Consequently, it omits fault 3 from
the "finely-tuned" list **35**.

In the simplified example depicted in **FIG. 3**, the
10 aggregate bitmap has been substantially simplified to
include only one failure pattern for descriptive purposes.
Also, the fault sources resulting in device failures have
also been simplified so that only one fault source is
identified as causing that one failure pattern. In
15 practice, however, it is to be appreciated that a device
test bitmap may include multiple failure patterns and the
fault sources in the resulting "fine-tuned" list may include
more than one fault source for each identifiable failure
pattern in the device test bitmap. Regardless of such
20 simplification in the example, however, it is readily
appreciated that application of the teachings described in
reference to **FIGS. 1~3** are equally applicable to such more
practical and complex situations.

Although the various aspects of the present
25 invention have been described with respect to a preferred
embodiment, it will be understood that the invention is
entitled to full protection within the full scope of the
appended claims.